

# On Liouville integrable defects

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- Work in collaboration with J. Avan.

- Integrable defects (quantum level) impose severe constraints on relevant algebraic and physical quantities (e.g. scattering amplitudes) (*Delfino, Mussardo, Simonetti, Konic, LeClair, ....*)
- In discrete integrable systems there is a systematic description of local defects based on QISM
- In integrable field theories a defect is introduced as discontinuity plus gluing conditions (*Bowcock, Corrigan, Zambon,...*), integrability issue not systematically addressed; other attempts (*Caudrelier, Kundu, Habibulin,...*)
- We developed a systematic *algebraic* means to investigate integrable field theories with point like defects. Integrability is ensured by construction

- 1 The general frame
  - The  $L$  matrix
  - The classical quadratic algebra
- 2 Local integrals of motion, and relevant Lax pairs for NLS and sine-Gordon models
- 3 Discrete theories and consistent continuum limits
- 4 Discussion and future perspectives

**The Lax pair**  $\mathbb{U}$ ,  $\mathbb{V}$ ; the linear auxiliary problem (e.g. *Faddeev-Takhtajan*):

$$\begin{aligned}\frac{\partial \Psi(x, t)}{\partial x} &= \mathbb{U}(x, t) \Psi(x, t) \\ \frac{\partial \Psi(x, t)}{\partial t} &= \mathbb{V}(x, t) \Psi(x, t)\end{aligned}$$

Compatibility condition leads to

Zero curvature condition

$$\dot{\mathbb{U}}(x, t) - \mathbb{V}'(x, t) + [\mathbb{U}(x, t), \mathbb{V}(x, t)] = 0$$

Gives rise to the equations of motion of the system.

# The monodromy matrix

The continuum monodromy matrix

$$T(x, y, \lambda) = P \exp \left\{ \int_x^y dx \mathbb{U}(x) \right\}$$

Solution of the differential equation

$$\frac{\partial T(x, y)}{\partial x} = \mathbb{U}(x, t) T(x, y)$$

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$\mathbb{U}$  obeys linear classical algebra,  $T$  satisfies the:

Classical algebra

$$\left\{ T_a(\lambda), T_b(\mu) \right\} = \left[ r_{ab}(\lambda - \mu), T_a(\lambda) T_b(\mu) \right]$$

The classical  $r$ -matrix satisfies the CYBE (*Sklyanin, Semenov-Tian-Shansky*)

$$\left[ r_{12}, r_{13} \right] + \left[ r_{12}, r_{23} \right] + \left[ r_{13}, r_{23} \right] = 0.$$

# Classical integrability

The monodromy matrix  $T$  satisfies the classical algebra, thus

The transfer matrix

$$t(\lambda) = \text{Tr } T(\lambda)$$

provides the charges in involution;

$$\{t(\lambda), t(\mu)\} = 0$$

integrability ensured by construction. In  $t(\lambda) \rightarrow$  *local* integrals of motion

# The defect frame

**The key object**, modified monodromy:

Defect monodromy matrix

$$T(L, -L, \lambda) = T^+(L, x_0, \lambda) \tilde{L}(x_0, \lambda) T^-(x_0, -L, \lambda)$$

where we define

$$T^\pm = P \exp \left\{ \int dx \mathbb{U}^\pm(x) \right\}$$

The defect  $\tilde{L}$  matrix obeys

$$\left\{ \tilde{L}_a(\lambda_1), \tilde{L}_b(\lambda_2) \right\} = \left[ r_{ab}(\lambda_1 - \lambda_2), L_a(\lambda_1) L_b(\lambda_2) \right]$$

$T^\pm$  satisfy the classical algebra, thus  $T$  obeys the same algebra, integrability also ensured



# The defect frame

Auxiliary linear problem for  $\mathbb{U}^\pm$ ,  $\mathbb{V}^\pm$  for the defect theory:

$$\frac{\partial \Psi(x, t)}{\partial x} = \mathbb{U}^\pm \Psi(x, t)$$
$$\frac{\partial \Psi(x, t)}{\partial t} = \mathbb{V}^\pm \Psi(x, t)$$

The corresponding

## Zero curvature condition

$$\dot{\mathbb{U}}^\pm(x, t) - \mathbb{V}^{\pm'}(x, t) + [\mathbb{U}^\pm(x, t), \mathbb{V}^\pm(x, t)] = 0 \quad x \neq x_0$$

# The defect frame

Auxiliary linear problem for  $\mathbb{U}^\pm$ ,  $\mathbb{V}^\pm$  for the defect theory:

$$\begin{aligned}\frac{\partial \Psi(x, t)}{\partial x} &= \mathbb{U}^\pm \Psi(x, t) \\ \frac{\partial \Psi(x, t)}{\partial t} &= \mathbb{V}^\pm \Psi(x, t)\end{aligned}$$

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$$\dot{\mathbb{U}}^\pm(x, t) - \mathbb{V}^{\pm'}(x, t) + [\mathbb{U}^\pm(x, t), \mathbb{V}^\pm(x, t)] = 0 \quad x \neq x_0$$

On the defect point

Defect zero curvature condition

$$\frac{d\tilde{L}(x_0)}{dt} = \tilde{\mathbb{V}}^+(x_0)\tilde{L}(x_0) - \tilde{L}(x_0)\tilde{\mathbb{V}}^-(x_0)$$

# The NLS model with defect

The  $\mathbb{U}^\pm$ -operator for the NLS model:

$$\mathbb{U}^\pm = \frac{\lambda}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} + \begin{pmatrix} 0 & \bar{\psi}^\pm \\ \psi^\pm & 0 \end{pmatrix}.$$

From the classical algebra for  $\mathbb{U}$ :

Poisson structure

$$\left\{ \psi^\pm(x), \bar{\psi}^\pm(y) \right\} = \delta(x - y), \quad \left\{ \psi^\mp(x), \bar{\psi}^\pm(y) \right\} = 0.$$

The classical  $r$ -matrix is the Yangian:  $r(\lambda) = \frac{1}{\lambda} \mathcal{P}$  (Yang)

$$\mathcal{P}(a \otimes b) = b \otimes a.$$

# The NLS model with defect

The generic defect  $\tilde{L}$  operator

$$\tilde{L}(x_0) = \lambda \mathbb{I} + \begin{pmatrix} \alpha(x_0) & \beta(x_0) \\ \gamma(x_0) & \delta(x_0) \end{pmatrix}.$$

From the quadratic classical algebra for  $\tilde{L}$  ( $\mathfrak{sl}_2$  algebra):

$$\{\alpha(x_0), \beta(x_0)\} = \beta(x_0)$$

$$\{\alpha(x_0), \gamma(x_0)\} = -\gamma(x_0)$$

$$\{\beta(x_0), \gamma(x_0)\} = 2\alpha(x_0)$$

Establish the Poisson structure!

- Relevant studies: (*Corrigan-Zambon*)

# The NLS model: local IM

First recall that:

$$\frac{\partial T^\pm(x, y, t)}{\partial x} = \mathbb{U}^\pm(x, t) T^\pm(x, y, t)$$

Based on the latter consider the decomposition ansatz:

$$T^\pm(x, y; \lambda) = (1 + W^\pm(x))e^{Z^\pm(x, y)}(1 + W^\pm(y))^{-1}$$

$W^\pm$  anti-diagonal,  $Z^\pm$  diagonal. Also,

$$W^\pm = \sum_{n=0}^{\infty} \frac{W^{\pm(n)}}{\lambda^n}, \quad Z^\pm = \sum_{n=-1}^{\infty} \frac{Z^{\pm(n)}}{\lambda^n}$$

Substituting the ansatz to the differential equation above identify  $W^{\pm(n)}$ ,  $Z^{\pm(n)}$  matrices.

# The NLS model: local IM

Substitution leads to *Riccati-type*:

Differential equations

$$\frac{dW^\pm}{dx} + W^\pm \mathbb{U}_d - \mathbb{U}_d W^\pm + W^\pm \mathbb{U}_a^\pm W^\pm - \mathbb{U}_a^\pm = 0$$

$$\frac{dZ^\pm}{dx} = \mathbb{U}_d + \mathbb{U}_a^\pm W^\pm$$

Solving the latter one identifies the  $W^{\pm(n)}$ ,  $Z^{\pm(n)}$ , hence the charges in involution.

- Similar differential equations arise within the inverse scattering frame.

# The NLS model: local IM

The generating function

$$\mathcal{G}(\lambda) = \ln \operatorname{tr}(T^+(\lambda) \tilde{L}(\lambda, x_0) T^-(\lambda))$$

which turns to, via the decomposition:

Generating function

$$\mathcal{G}(\lambda) = Z_{11}^+(\lambda) + Z_{11}^-(\lambda) + \ln[(1 + W^+(x_0))^{-1} \tilde{L}(x_0) (1 + W^-(x_0))]_{11}$$

Also,

$$\mathcal{G}(\lambda) = \sum_{n=0}^{\infty} \frac{\mathcal{H}^{(n)}}{\lambda^n}$$

# The NLS model: local IM

The first three integrals of motion:

- **The number of particles**

$$\mathcal{H}^{(1)} = \int_{-L}^{x_0^-} dx \psi^-(x) \bar{\psi}^-(x) + \int_{x_0^+}^L dx \psi^+(x) \bar{\psi}^+(x) + \alpha(x_0)$$

- **The momentum**

$$\begin{aligned} \mathcal{H}^{(2)} &= - \int_{-L}^{x_0^-} dx \bar{\psi}^-(x) \psi^{-\prime}(x) - \int_{x_0^+}^L dx \bar{\psi}^+(x) \psi^{+\prime}(x) \\ &\quad - \bar{\psi}^+ \psi^+ + \bar{\psi}^+ \psi^- + \gamma \bar{\psi}^+ + \beta \psi^- - \frac{\alpha^2}{2} \end{aligned}$$



- The Hamiltonian

$$\begin{aligned}\mathcal{H}^{(3)} &= \int_{x_0^+}^L dx \left( \bar{\psi}^+ \psi^{+\prime\prime} + |\psi^+|^4 \right) + \int_{-L}^{x_0^-} dx \left( \bar{\psi}^- \psi^{-\prime\prime} + |\psi^-|^4 \right) \\ &+ (\bar{\psi}^+ \psi^+)' + \gamma \bar{\psi}^{+\prime} - \beta \psi^{-\prime} + \bar{\psi}^{+\prime} \psi^- + \frac{\alpha^3}{3} \\ &- \bar{\psi}^+ \psi^{-\prime} - \alpha \left( \gamma \bar{\psi}^+ + \beta \psi^- + 2 \bar{\psi}^+ \psi^- \right)\end{aligned}$$

- **The Hamiltonian**

$$\begin{aligned}\mathcal{H}^{(3)} &= \int_{x_0^+}^L dx \left( \bar{\psi}^+ \psi^{+\prime\prime} + |\psi^+|^4 \right) + \int_{-L}^{x_0^-} dx \left( \bar{\psi}^- \psi^{-\prime\prime} + |\psi^-|^4 \right) \\ &+ (\bar{\psi}^+ \psi^+)' + \gamma \bar{\psi}^{+\prime} - \beta \psi^{-\prime} + \bar{\psi}^{+\prime} \psi^- + \frac{\alpha^3}{3} \\ &- \bar{\psi}^+ \psi^{-\prime} - \alpha \left( \gamma \bar{\psi}^+ + \beta \psi^- + 2 \bar{\psi}^+ \psi^- \right)\end{aligned}$$

By construction (formally), and also explicitly checked:

Involution

$$\left\{ \mathcal{H}_1, \mathcal{H}_2 \right\} = \left\{ \mathcal{H}_1, \mathcal{H}_3 \right\} = \left\{ \mathcal{H}_2, \mathcal{H}_3 \right\} = 0$$

No sewing constraints arise or used so far, *off-shell* integrability.

# The NLS model: Lax pair

Next step, derive time component of the Lax pair  $\mathbb{V}$ , and sewing conditions. Explicit expressions (*Faddeev-Takhtajan, Avan-Doikou*):

$$\mathbb{V}^+(x, \lambda, \mu) = t^{-1} \text{tr}_a \left( T_a^+(L, x) r_{ab}(\lambda - \mu) T_a^+(x, x_0) \tilde{L}_a(x_0) T_a^-(x_0, -L) \right)$$

$$\mathbb{V}^-(x, \lambda, \mu) = t^{-1} \text{tr}_a \left( T_a^+(L, x_0) \tilde{L}_a(x_0) T_a^-(x_0, x) r_{ab}(\lambda - \mu) T_a^-(x, -L) \right)$$

$$\tilde{\mathbb{V}}^+(x_0, \lambda, \mu) = t^{-1} \text{tr}_a \left( T_a^+(L, x_0) r_{ab}(\lambda - \mu) \tilde{L}_a(x_0) T_a^-(x_0, -L) \right)$$

$$\tilde{\mathbb{V}}^-(x_0, \lambda, \mu) = t^{-1} \text{tr}_a \left( T_a^+(L, x_0) \tilde{L}_a(x_0) r_{ab}(\lambda - \mu) T_a^-(x_0, -L) \right).$$

# The NLS model: Lax pair

For the left and right bulk theories, and the defect point:

$$\mathbb{V}^{\pm(1)}(\mu, x) = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\mathbb{V}^{-(2)}(\mu, x) = \begin{pmatrix} \mu & \bar{\psi}^-(x) \\ \psi^-(x) & 0 \end{pmatrix}$$

$$\mathbb{V}^{+(2)}(\mu, x) = \begin{pmatrix} \mu & \bar{\psi}^+(x) \\ \psi^+(x) & 0 \end{pmatrix}$$

$$\tilde{\mathbb{V}}^{-(2)}(\mu, x_0) = \begin{pmatrix} \mu & \bar{\psi}^+(x_0) + \beta(x_0) \\ \psi^-(x_0) & 0 \end{pmatrix}$$

$$\tilde{\mathbb{V}}^{+(2)}(\mu, x_0) = \begin{pmatrix} \mu & \bar{\psi}^+(x_0) \\ \gamma(x_0) + \psi^-(x_0) & 0 \end{pmatrix}$$

# The NLS model: Lax pair

$$\mathbb{V}^{-(3)}(\mu, x) = \begin{pmatrix} \mu^2 - \bar{\psi}^-(x)\psi^-(x) & \mu\bar{\psi}^-(x) + \bar{\psi}'^-(x) \\ \mu\psi^-(x) - \psi'^-(x) & \bar{\psi}^-(x)\psi^-(x) \end{pmatrix}$$

$$\mathbb{V}^{+(3)}(\mu, x) = \begin{pmatrix} \mu^2 - \bar{\psi}^+(x)\psi^+(x) & \mu\bar{\psi}^+(x) + \bar{\psi}'^+(x) \\ \mu\psi^+(x) - \psi'^+(x) & \bar{\psi}^+(x)\psi^+(x) \end{pmatrix}$$

$$\tilde{\mathbb{V}}^{-(3)}(x_0) = \begin{pmatrix} \mu^2 - (\bar{\psi}^+(x_0) + \beta(x_0))\psi^-(x_0) & \mu(\bar{\psi}^+(x_0) + \beta(x_0)) + \mathbf{f}(x_0) \\ \mu\psi^-(x_0) - \psi'^-(x_0) & (\bar{\psi}^+(x_0) + \beta(x_0))\psi^-(x_0) \end{pmatrix}$$

$$\tilde{\mathbb{V}}^{+(3)}(x_0) = \begin{pmatrix} \mu^2 - \bar{\psi}^+(x_0)(\psi^-(x_0) + \gamma(x_0)) & \mu\bar{\psi}^+(x_0) + \bar{\psi}'^+(x_0) \\ \mu(\psi^-(x_0) + \gamma(x_0)) + \mathbf{g}(x_0) & \bar{\psi}^+(x_0)(\psi^-(x_0) + \gamma(x_0)) \end{pmatrix}$$

where we define

$$\mathbf{f}(x_0) = \bar{\psi}'^+(x_0) - \alpha(x_0)(\beta(x_0) + 2\bar{\psi}^+(x_0))$$

$$\mathbf{g}(x_0) = -\psi'^-(x_0) - \alpha(x_0)(\gamma(x_0) + 2\psi^-(x_0))$$

# The NLS model: Equations of motion

Derive the equations of motion via the Hamiltonian:

## Equations of motion

$$\begin{aligned}\dot{\psi}^{\pm}(x, t) &= \{\mathcal{H}^{(j)}, \psi^{\pm}(x, t)\}, & \dot{\bar{\psi}}^{\pm}(x, t) &= \{\mathcal{H}^{(j)}, \bar{\psi}^{\pm}(x, t)\} \\ \dot{e}(x_0, t) &= \{\mathcal{H}^{(j)}, e(x_0, t)\}, & e &\in \{\alpha, \beta, \gamma\}, \quad x \neq x_0\end{aligned}$$

# The NLS model: Equations of motion

Derive the equations of motion via the Hamiltonian:

## Equations of motion

$$\begin{aligned}\dot{\psi}^{\pm}(x, t) &= \{\mathcal{H}^{(j)}, \psi^{\pm}(x, t)\}, & \dot{\bar{\psi}}^{\pm}(x, t) &= \{\mathcal{H}^{(j)}, \bar{\psi}^{\pm}(x, t)\} \\ \dot{e}(x_0, t) &= \{\mathcal{H}^{(j)}, e(x_0, t)\}, & e &\in \{\alpha, \beta, \gamma\}, \quad x \neq x_0\end{aligned}$$

The latter lead to the familiar E.M. for  $\mathcal{H}^{(3)}$

$$\begin{aligned}\dot{\psi}^{\pm}(x, t) &= \frac{\partial^2 \psi^{\pm}(x, t)}{\partial x^2} - 2|\psi^{\pm}(x, t)|^2 \psi^{\pm}(x, t) \\ \dot{\bar{\psi}}^{\pm}(x, t) &= \frac{\partial^2 \bar{\psi}^{\pm}(x, t)}{\partial x^2} - 2|\psi^{\pm}(x, t)|^2 \bar{\psi}^{\pm}(x, t)\end{aligned}$$

Plus E.M. on the defect point. Consistency check via the zero curvature condition.

# The NLS model: sewing conditions

Due to continuity requirements at the points  $x_0^+$ ,  $x_0^-$ :

## Continuity

$$\mathbb{V}^{+(k)}(x_0^+) \rightarrow \tilde{\mathbb{V}}^{+(k)}(x_0), \quad \mathbb{V}^{-(k)}(x_0^-) \rightarrow \tilde{\mathbb{V}}^{-(k)}(x_0), \quad x_0^\pm \rightarrow x_0$$



# The NLS model: sewing conditions

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The following sewing conditions  $C_\pm^{(k)}$  arise

$$C_-^{(1)} : \quad \bar{\psi}^-(x_0) - \bar{\psi}^+(x_0) - \beta(x_0) = 0,$$

$$C_+^{(1)} : \quad \psi^+(x_0) - \psi^-(x_0) - \gamma(x_0) = 0$$

$$C_-^{(2)} : \quad \bar{\psi}^{-'}(x_0) - \bar{\psi}^{+'}(x_0) + \alpha(x_0)\beta(x_0) + 2\alpha(x_0)\bar{\psi}^+(x_0) = 0$$

$$C_+^{(2)} : \quad \psi^{-'}(x_0) - \psi^{+'}(x_0) + \alpha(x_0)\gamma(x_0) + 2\alpha(x_0)\psi^-(x_0) = 0$$

...

**Jump** across the defect point!

# The NLS model: sewing conditions

## Main proposition:

### Compatibility

$$\left\{ \mathcal{H}^{(k)}, \mathcal{C}_{\pm}^{(m,l)} \right\} = \sum_{i=0}^{k-1} \left[ \mathcal{C}_{\pm}^{(k,i)}, \mathbb{V}^{\pm(m+i,l)}(x_0^{\pm}) \right] + \sum_{i=0}^{k-1} \left[ \tilde{\mathbb{V}}^{\pm(k,i)}(x_0), \mathcal{C}_{\pm}^{(m+i,l)} \right]$$

- $\mathcal{C}_{\pm}^{(p,l)}$  matrices with entries the constraints. Proof based on the form of  $\mathbb{V}$ , and the underlying algebra.
- Sub-manifold of sewing conditions (dynamical constraints) invariant under the Hamiltonian action!

# The sine-Gordon model with defect

The  $\mathbb{U}$ -operator for the sine-Gordon model:

$$\mathbb{U}(x, t, u) = \frac{\beta}{4i} \pi(x, t) \sigma^z + \frac{mu}{4i} e^{\frac{i\beta}{4} \phi \sigma^z} \sigma^y e^{-\frac{i\beta}{4} \phi \sigma^z} - \frac{mu^{-1}}{4i} e^{-\frac{i\beta}{4} \phi \sigma^z} \sigma^y e^{\frac{i\beta}{4} \phi \sigma^z}$$

$u \equiv e^\lambda$ ,  $\sigma^{x,y,z}$  Pauli matrices. The  $r$ -matrix (*Faddeev-Takhtajan, Sklyanin*):

$$r(\lambda) = \frac{\beta^2}{8 \sinh \lambda} \begin{pmatrix} \frac{\sigma^z + 1}{2} \cosh \lambda & \sigma^- \\ \sigma^+ & \frac{-\sigma^z + 1}{2} \cosh \lambda \end{pmatrix}.$$

$\mathbb{U}$  satisfies the linear Poisson algebra leads:

$$\left\{ \phi(x), \pi(y) \right\} = \delta(x - y)$$

# The sine-Gordon model with defect

The relevant defect matrix (type II)

$$\tilde{L}(\lambda) = \begin{pmatrix} e^\lambda V - e^{-\lambda} V^{-1} & \bar{a} \\ a & e^\lambda V^{-1} - e^{-\lambda} V \end{pmatrix}.$$

$\tilde{L}$  satisfies the classical algebra, hence:

$$\begin{aligned} \{V, \bar{a}\} &= \frac{\beta^2}{8} V \bar{a}, \\ \{V, a\} &= -\frac{\beta^2}{8} Va, \\ \{\bar{a}, a\} &= \frac{\beta^2}{4} (V^2 - V^{-2}) \end{aligned}$$

- Relevant studies: (*Bowcock-Corrigan-Zambon, Caudrelier, Habibulin-Kundu, Aguirre et al.*)

# The sine-Gordon: local IM

Recall the generating function of the local IM

$$\mathcal{G}(\lambda) = \ln \operatorname{tr}(T^+ \tilde{L} T^-)$$

Generating function

$$\mathcal{G}(\lambda) = Z_{11}^+ + Z_{11}^- + \ln \left[ (1 + W^+)^{-1} (\Omega^+(x_0))^{-1} \tilde{L}(x_0) \Omega^-(x_0) (1 + W^-) \right]_{11}$$

$$\Omega^\pm = e^{\frac{i\beta}{4} \phi^\pm \sigma^z}.$$

Expanding the latter expression in powers of  $u^{-1}$  we obtain the following:

$$\mathcal{G}(\lambda) = \sum_{m=0}^{\infty} \frac{\mathcal{I}^{(m)}}{u^m}$$

# The sine-Gordon: local IM

The first charge (the  $u^{-1}$ -expansion) leads to  $\mathcal{I}^{(1)}$ , the  $u$ -expansion leads to  $\mathcal{I}^{(-1)}$ :

$$\mathcal{I}^{(-1)}(\phi, \pi, V, a, \bar{a}) = \mathcal{I}^{(1)}(-\phi, \pi, V^{-1}, a, \bar{a})$$

Define the

Hamiltonian

$$\begin{aligned}\mathcal{H} &= \frac{2im}{\beta^2} (\mathcal{I}^{(1)} - \mathcal{I}^{(-1)}) \\ &= \int_{-L}^{x_0^-} dx \left( \frac{1}{2} (\pi^{-2}(x) + \phi^{-\prime 2}(x)) - \frac{m^2}{\beta^2} \cos(\beta\phi^-(x)) \right) \\ &+ \int_{x_0^+}^L dx \left( \frac{1}{2} (\pi^{+2}(x) + \phi^{+\prime 2}(x)) - \frac{m^2}{\beta^2} \cos(\beta\phi^+(x)) \right) \\ &+ \frac{4m}{\beta^2 \mathcal{D}} \cos \frac{\beta}{4} (\phi^+ + \phi^-) (\bar{a} - a) + \frac{2i}{\beta \mathcal{D}} (\phi^{+'} + \phi^{-'}) \mathcal{A}\end{aligned}$$

# The sine-Gordon: local IM

Also derive the:

## Momentum

$$\begin{aligned}\mathcal{P} &= \frac{2im}{\beta^2} (\mathcal{I}^{(1)} + \mathcal{I}^{(-1)}) \\ &= \int_{-L}^{x_0^-} dx \phi^{-'}(x) \pi^-(x) + \int_{x_0^+}^L dx \phi^{+'}(x) \pi^+(x) \\ &= \frac{4mi}{\beta^2 \mathcal{D}} \sin \frac{\beta}{4} (\phi^+ + \phi^-) (\bar{a} + a) + \frac{2i}{\beta \mathcal{D}} (\pi^+ + \pi^-) \mathcal{A}\end{aligned}$$

$$\mathcal{D} = Ve^{-\frac{i\beta}{4}(\phi^+ - \phi^-)} + V^{-1}e^{\frac{i\beta}{4}(\phi^+ - \phi^-)}$$

$$\mathcal{A} = Ve^{-\frac{i\beta}{4}(\phi^+ - \phi^-)} - V^{-1}e^{\frac{i\beta}{4}(\phi^+ - \phi^-)}$$

- Commutativity among the IM will be discussed later.

# The sine-Gordon: the Lax pair

From the explicit expression for the  $\mathbb{V}$  operators we find for the left and right bulk theories:

$$\mathbb{V}_{\mathcal{H}}^{\pm} = \frac{\beta}{4i} \phi^{\pm'} \sigma^z + \frac{vm}{4i} \Omega^{\pm} \sigma^y (\Omega^{\pm})^{-1} + \frac{v^{-1}m}{4i} (\Omega^{\pm})^{-1} \sigma^y \Omega^{\pm}$$

$$\mathbb{V}_{\mathcal{P}}^{\pm} = \frac{\beta}{4i} \pi^{\pm} \sigma^z + \frac{vm}{4i} \Omega^{\pm} \sigma^y (\Omega^{\pm})^{-1} - \frac{v^{-1}m}{4i} (\Omega^{\pm})^{-1} \sigma^y \Omega^{\pm}$$

Computation of the  $\mathbb{V}$  operators on the defect point leads to

$$\tilde{\mathbb{V}}_{\mathcal{H}}^{\pm} = \mathbb{V}_{\mathcal{H}}^{\pm} + \delta_{\mathcal{H}}$$

$$\tilde{\mathbb{V}}_{\mathcal{P}}^{\pm} = \mathbb{V}_{\mathcal{P}}^{\pm} + \delta_{\mathcal{P}}$$



# The sine-Gordon: sewing conditions

Continuity requirements around the defect point

$$\delta_{\mathcal{H}} \rightarrow 0, \quad \delta_{\mathcal{P}} \rightarrow 0$$

lead to:

## Sewing conditions

$$S_1 : \quad V = e^{\frac{i\beta}{4}(\phi^+ - \phi^-)}$$

$$S_2 : \quad \pi^+(x_0) - \pi^-(x_0) = \frac{im}{\beta} \cos \frac{\beta}{4}(\phi^+(x_0) + \phi^-(x_0)) (a + \bar{a})$$

$$S_2' : \quad \phi^{+'}(x_0) - \phi^{-'}(x_0) = \frac{m}{\beta} \sin \frac{\beta}{4}(\phi^+(x_0) + \phi^-(x_0)) (\bar{a} - a)$$

- *Jump* across the defect point!
- E.M. from Hamiltonian and zero curvature condition coincide.

# The sine-Gordon: commutativity

Commutativity among the IM, explicitly checked, formally guaranteed

Commutativity

$$\{\mathcal{H}, \mathcal{P}\} = 0$$

- The latter is proven using the sewing conditions, i.e. Dirac (not Poisson) commutativity! *On-shell* integrability.
- In NLS *off-shell* integrability

$$\{\mathcal{I}_1, \mathcal{I}_2\} = 0$$

no use of constraints. Issue related to suitable continuum limits!

# The continuum limit

Integrable continuum limit (see e.g. *Avan-Doikou-Sfetsos*): The discrete monodromy matrix:

$$T_0(\lambda) = L_{0N}(\lambda) \dots L_{02}(\lambda) L_{01}(\lambda)$$

$L$  and  $T$  satisfy the classical quadratic algebra

$$\{L_a(\lambda), L_b(\lambda')\} = [r_{ab}(\lambda - \lambda'), L_a(\lambda)L_b(\lambda')]$$

Hence, integrability is guaranteed!

# The continuum limit

Consider the identifications:

$$L_n \rightarrow 1 + \delta U(x), \quad \mathbb{A}_n \rightarrow \mathbb{V}(x), \quad \mathbb{A}_{n+1} \rightarrow \mathbb{V}(x + \delta)$$

The *discrete* zero curvature condition:

$$\dot{L}_j = \mathbb{A}_{j+1} L_j - L_j \mathbb{A}_j$$

takes the familiar continuum form:

Continuum zero curvature

$$\dot{U} - V' + [U, V] = 0$$

We have kept terms proportional to  $\delta$  in the discrete zero curvature condition.

# The continuum limit

Recall

$$L_{ai} = 1 + \delta \mathbb{U}_{ai} + \mathcal{O}(\delta^2) ,$$

Then the monodromy matrix is expanded as:

$$T_a = 1 + \delta \sum_i \mathbb{U}_{ai} + \delta^2 \sum_{i < j} \mathbb{U}_{ai} \mathbb{U}_{aj} + \dots .$$

Use also

$$\delta \sum_{j=1} f_j \rightarrow \int_{-L}^L dx f(x)$$

which leads to the familiar continuum expression

The continuum monodromy

$$T(\lambda) = P \exp \left( \int_{-L}^L dx \mathbb{U}(x) \right)$$

# The continuum limit

Then the discrete monodromy matrix in the *presence of defect*:

$$T_a(\lambda) = L_{aN}(\lambda) \dots \tilde{L}_{an}(\lambda) \dots L_{a1}(\lambda)$$

according to previous analysis  $T$  will be formally expressed at the continuum limit:

## The defect monodromy

$$T(\lambda) = P \exp \left( \int_{-L}^{x_0^-} dx \mathbb{U}^-(x) \right) \tilde{L}(\lambda, x_0) P \exp \left( \int_{x_0^+}^L dx \mathbb{U}^+(x) \right)$$

# The continuum limit

The zero curvature condition for the left-right bulk theories:

$$\dot{U}^\pm - V_{\pm}' + [U^\pm, V^\pm] = 0$$

The zero curvature condition on the *defect point*, discrete:

$$\check{L}_n(\lambda) = \mathbb{A}_{n+1} \tilde{L}_n(\lambda) - \tilde{L}_n(\lambda) \mathbb{A}_n(\lambda)$$

Recalling the latter identifications obtain:

## Continuum limit

$$\check{L}(x_0, \lambda) = V^+(x_0, \lambda) \tilde{L}(x_0, \lambda) - \tilde{L}(x_0, \lambda) V^-(x_0, \lambda)$$

- In NLS: (*Doikou, Avan-Doikou*)

# The discrete NLS

The DNLS  $L$ -matrix

$$L(\lambda) = \begin{pmatrix} 1 + \delta\lambda - \delta^2 x X & \Delta x \\ -\delta X & 1 \end{pmatrix}$$

$$\tilde{L}(\lambda) = \delta\lambda + \delta \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix}$$

Introduce:

$$\begin{aligned} x_j &\rightarrow \bar{\psi}^-(x), & X_j &\rightarrow -\psi^-(x), & 1 \leq j \leq n-1, & x \in (-L, x_0) \\ x_j &\rightarrow \bar{\psi}^+(x), & X_j &\rightarrow -\psi^+(x), & n+1 \leq j \leq N, & x \in (x_0, L) \end{aligned}$$

Obtain the continuum NLS  $\mathbb{U}$ -matrix.

- Discrete NLS: (*Doikou*)



# The discrete NLS

The first IM for DNLS:

$$H^{(1)} = - \sum_{j \neq n} x_j X_j + \alpha_n$$

$$H^{(2)} = - \sum_{j \neq n, n-1} x_{j+1} X_j - \frac{1}{2} \sum_{j \neq n} \mathbb{N}_j^2 - x_{n+1} X_{n-1} - \beta_n X_{n-1} + \gamma_n X_{n+1} - \frac{\alpha_n^2}{2}$$

$\mathbb{N}_j = 1 - x_j X_j$ . The continuum limit immediately leads to the familiar NLS expressions. Extra consistency check!

# The discrete NLS

The  $\mathbb{A}$ -operators:

$$\mathbb{A}_j^{(1)}(\mu) = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

$\mathbb{A}_j^{(2)}$  for  $j \neq n, n+1$  is given by

$$\mathbb{A}_j^{(2)}(\mu) = \begin{pmatrix} \mu & x_j \\ -X_{j-1} & 0 \end{pmatrix},$$

whereas

$$\mathbb{A}_n^{(2)} = \begin{pmatrix} \mu & \beta_n + x_{n+1} \\ -X_{n-1} & 0 \end{pmatrix}, \quad \mathbb{A}_{n+1}^{(2)} = \begin{pmatrix} \mu & x_{n+1} \\ \gamma_n - X_{n-1} & 0 \end{pmatrix}.$$

The continuum limit leads to the familiar NLS expressions for the  $\mathbb{V}$ -operators.

# The NLS model: Lax pair

For the left and right bulk theories, and the defect point:

$$\mathbb{V}^{\pm(1)}(\mu, x) = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\mathbb{V}^{-(2)}(\mu, x) = \begin{pmatrix} \mu & \bar{\psi}^-(x) \\ \psi^-(x) & 0 \end{pmatrix}$$

$$\mathbb{V}^{+(2)}(\mu, x) = \begin{pmatrix} \mu & \bar{\psi}^+(x) \\ \psi^+(x) & 0 \end{pmatrix}$$

$$\tilde{\mathbb{V}}^{-(2)}(\mu, x_0) = \begin{pmatrix} \mu & \bar{\psi}^+(x_0) + \beta(x_0) \\ \psi^-(x_0) & 0 \end{pmatrix}$$

$$\tilde{\mathbb{V}}^{+(2)}(\mu, x_0) = \begin{pmatrix} \mu & \bar{\psi}^+(x_0) \\ \gamma(x_0) + \psi^-(x_0) & 0 \end{pmatrix}$$

# Discussion

- Deeper understanding of the *off-shell* vs *on-shell* integrability; related to suitable continuum limits.
- Extend the study to other classical integrable models with defects e.g. (an)isotropic Heisenberg chains, sigma models, and higher rank generalizations.
- Study of extended (not point like) defects, and defects associated to *non-ultra-local* algebras. Investigate also non-dynamical defects.
- At the quantum level: derive the associated transmission amplitudes via the Bethe ansatz equations.